# SERVICE MANUAL 1571 DISK DRIVE

**Preliminary** 

OCTOBER 1986 PN-314002-04

### Commodore Business Machines, Inc.

1200 Wilson Drive, West Chester, Pennsylvania 19380 U.S.A.

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## COMMODORE 1571 DISK DRIVE SPECIFICATIONS

#### **GENERAL FEATURES**

- 5-1/4" Floppy Disk Drive
- Supports Fast Data Transfer Rates
- Two Serial Ports for Adding Peripherals
- Software Disk Format Selectable
- Comes with Serial and Power Cables Compatible with Commodore 128, Commodore 64, and Plus/4 Computers

#### **SYSTEM FEATURES**

- Built-in 6502 Microprocessor
- 2K RAM
- 32K ROM
- Built-in DOS
- Program Load Transfer Rates
  - 300 cps under C64 Control
  - 5200 cps Max under C128 Control (Burst Rate)
  - 5200 cps Max under CP/M® Control (Burst Rate)

## MEDIA CHARACTERISTICS

- Commodore Standard (GCR)
- Double Sided/Single Density
- 350K Storage Capacity (Formatted)
- Compatible with 1541 Disk Drive
- Supports Program, Sequential, Relative and User Files
- CP/M Compatible (MFM)
- Single or Double Sided/Double Density Formats
- Up to 410K Storage Capacity (Formatted)
- Read/Write Compatible with Kaypro®, Osborne®, IBM®, CP/M® 86, Epson® QX-10 and Numerous Other Formats
- Supports Most CP/M® Files

#### **INPUTS/OUTPUTS**

- Two Serial Ports
- Power Connector

#### **POWER REQUIREMENTS**

• 117 Volts AC, 60Hz, Less than 25 Watts

Specifications subject to change without notice.

CP/M is a registered trademark of Digital Research, Inc.

KayPro is a registered trademark of Kaypro, Inc.

Osborne is a registered trademark of Osborne Computer Corporation.

IBM is a registered trademark of International Business Machines

Epson is a registered trademark of Epson Corporation.

## PARTS LIST 1571

PLEASE NOTE: Commodore part numbers are provided for reference only and do not indicate the availability of parts from Commodore. Industry standard parts (Resistors, Capacitors, Connectors) should be secured locally. Approved cross-references for TTL-chips, Transistors, etc. are available in manual form through the Service Department. Unique or non-standard parts will be stocked by Commodore and are indicated on the parts list by a "C".

#### **TOP CASE ASSY**

Top Case	$\mathbf{C}$	3	1(	)5	0	8-	0	1

#### **BOTTOM CASE ASSY**

Bottom Case	C 310509-01
PCB Assembly	C 310420-01
Power Supply Assembly	C 250772-01
Drive Assembly - Newtronics	C 252083-01
Drive Assembly - Alps	C 252092-01
PCB Shield	C 252069-01
PCB Insulation Sheet	C 252070-01

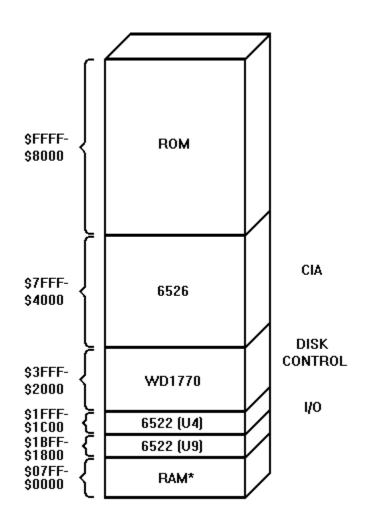
#### **FRONT CASE ASSY**

Front Bezel - Alps	C 252086-01
Front Bezel - Newtronics	C 310507-01
Disk Eject Lever	C 252050-01
LED Assembly	C 250754-04
LED Clip	C 252013-01
Nameplate	C 310411-01

#### **ACCESSORIES**

Users Manual	C 252095-01
Demo Disk	C 252093-01
Power Cord	C 252164-01 sub:
	C 903508-04
6-Pin Din Cable	C 252159-01 sub:
	C 1540027-01

## **MEMORY MAP**



<sup>\*</sup> ONLY 2K OF RAM SPACE AVAILABLE IN THE 1571 ADDRESS DECODING IS ACCOMPLISHED BY THE 64H157 GATE ARRAY.

## 20 PIN GATE ARRAY 1541B AND 1571

The 20 pin gate array used in the 1541B and 1571 disk drives is designed to work in conjunction with the 40/42 pin gate array also used in these drives. As illustrated in the block diagram, this I.C. controls 3 operations:

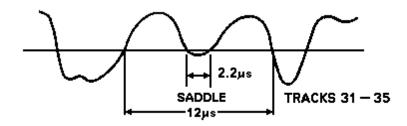
#### 1. ADDRESS SELECTOR

The function of the address selector is to produce ROM, RAM and I/O chip select signals by decoding the addresses A10, A12, A13, A14 and A15. The system clocks are not gated with the address lines in this I.C. All chip select outputs are ACTIVE LOW.

Address	Decode	Map:	RAME	0000	 07FF
			IO1	1800	 1BFF
			IO2	1C00	 1FFF
			CS1	2000	 3FFF
			CS2	4000	 7FFF
			ROME	C000	 FFFF

#### 2. SADDLE CANCELER

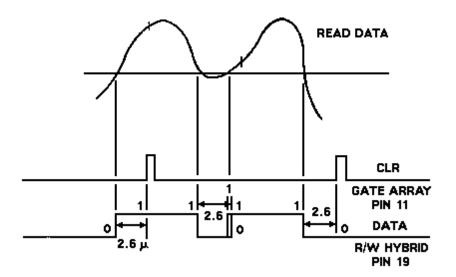
This correction signal is generated during the period that the data pattern is two consecutive zeros. With the Commodore GCR type recording format, a problem occurs in the waveform of the read signal. In the worst case pattern of 1001, a saddle condition will occur as illustrated below.



The worst case saddle will occur in tracks 31 to 35 and if not compensated for, will result in a read error. In the original 1541 drives, a one-shot was used to correct the condition; however, in this gate array it is corrected digitally.

The data output line, pin 19, of the R/W Hybrid's data comparitor is fed to the data input line, pin 3, of this gate array.

The data is then compared with the last data value which has been latched by the gate array, 2.6 usec after the rising or falling edge of the data line. If the current data value differs from the previous data value, the clear line is set to a high level for a duration of 63 nsec. If the values are the same, the clear line is not set.



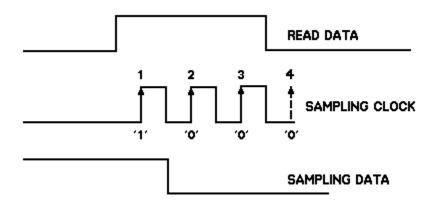
## 20 PIN GATE ARRAY (continued)

It takes 2.56 to 2.62 usec to cancel the saddle. If the saddle should be longer than this length of time, the saddle can not be corrected and will result in a read error. Also, if the time for correcting the saddle is set for a longer time interval, the clear signal will not be set when the data is equal to 11. Therefore, approximately 2.6 usec the most suitable time setting for saddle correction.

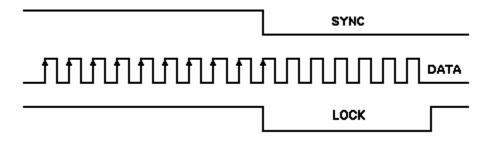
Note: The minimum bit rate for tracks 1 - 17 is equal to 2.6 usec. If this time should become less due to motor speed, the SYNC signal cannot be recognized on the outer tracks resulting in error.

#### 3. MOTOR SPEED COMPENSATOR (PLL)

This gate array detects the motor speed and generates an internal data sampling clock signal that matches with the motor speed (see below).

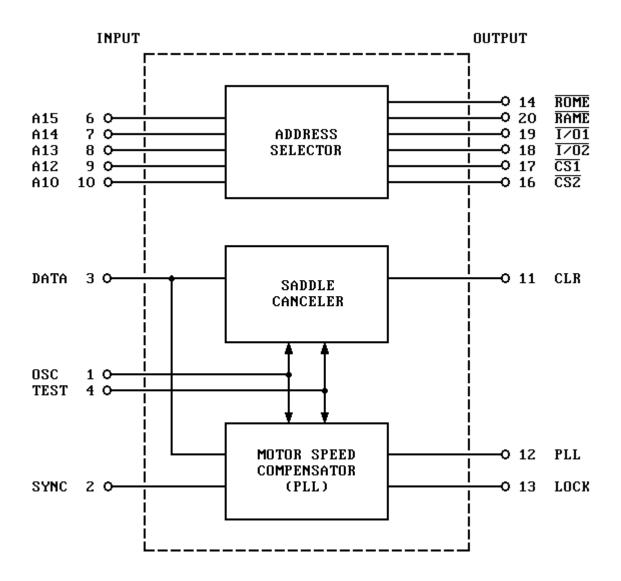


When the SYNC signal goes to the low level, the LOCK signal goes false and the sampling clock is switched to the internal clock signal of the gate array. Once the PLL has sampled the data one's, the LOCK signal will go high to indicate that the output of the PLL is valid. If the PLL cannot lock on, the internal clock signal will be used and the LOCK signal will remain at the low level. This can occur when the stepper is still moving or the spindle motor is not up to speed yet. In short, this allows the reading of data independent of motor speed within the lock on limits of the PLL.

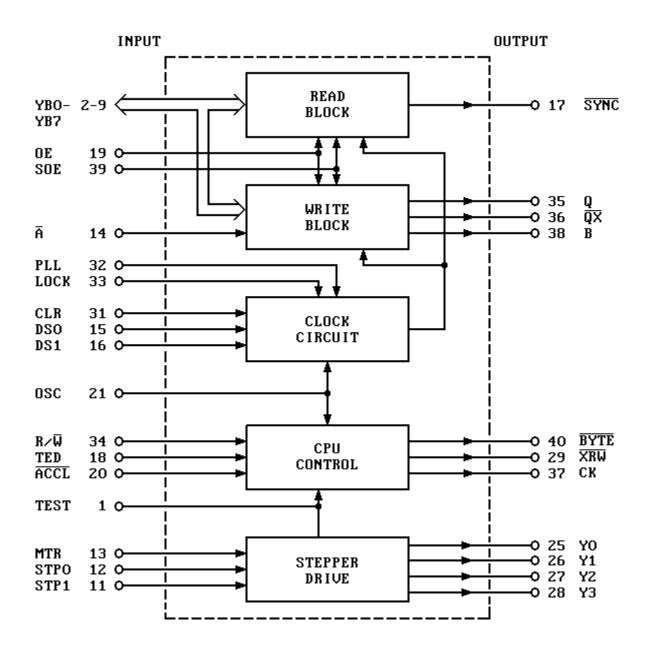


The 1571 runs on the SYSTEM CLOCK and does not implement the LOCK signal.

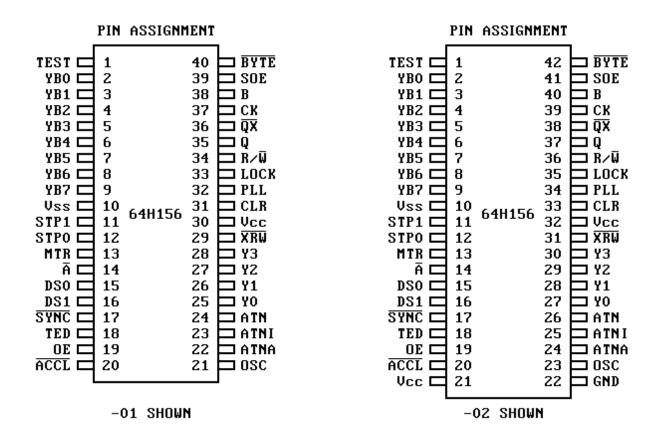
## 251829 BLOCK DIAGRAM 20 PIN GATE ARRAY FOR 1541B/1571



## 251828 BLOCK DIAGRAM 40/42 PIN GATE ARRAY FOR 1541B/1571



#### **40/42 PIN GATE ARRAY**



<b>40 PIN</b>	<b>42 PIN</b>	DESC	FUNCTION
1	1	TEST	Input used in design verification.
2-9	2-9	YB0-YB7	Data input/output lines for read/write operation.
10	10	Vss	Ground.
11,12	11,12	STP0,STP1	Input to stepper driver.
13	13	MTR	Control line used to activate the stepper motor.
14	14	A	Write protect input. Indicates disk is write protected.
15,16	15,16	DS0,DS1	Inputs used to produce the binary count for the frequency divide ratio.
17	17	SYNC	Sync output.
18	18	TED	A low input clears the BYTE line in 2 MHz mode. A high sets 1541 mode.
19	19	OE	Input to read/write block to set mode. 0 for Write, 1 for Read.
20	20	ACCL	Input select line for the CPU clock. 0 for 1541 - 1 MHz, 1 for 1571 - 2 MHz.
XX	21,22		N/C
21	23	OSC	16 MHz clock input.
22	24	ATNA	Attention acknowledge input.
23	25	ATNI	Attention line input from serial bus.
24	26	ATN	Attention data input from serial bus.
25-28	27-30	Y0-Y3	Control output lines for the 4 phases of the stepper motor.

29	31	XRW	RAM write enable output.
30	32	Vcc	+5VDC.
31	33	CLR	High input when the read data is logical 1.
32	34	PLL	Input from the 20 pin gate array. Clock compensation.
33	35	LOCK	Indicates the PLL LOCK status. When logical 1, PLL is locked. When
			0, the internal clock is used for sampling data.
34	36	R/W	R/W select input.
35,36	37,38	Q,Qx	Write pulse outputs.
37	39	CK	Clock select output - 1 or 2 MHz.
38	40	В	Write enable output.
39	41	SOE	Enable byte input.
40	42	BYTE	Data latched output.

## WD 1770/1772 FLOPPY DISK CONTROLLER/FORMATTER

PIN ASSIGNMENT					
CS	1 2 3 4 5 6 7 8 9 10 11 12 13	28 27 26 25 24 23 22 21 20 19 18 17 16	INTRQ DRQ DDEN IP TROO WB MB MB MC		
•			•		

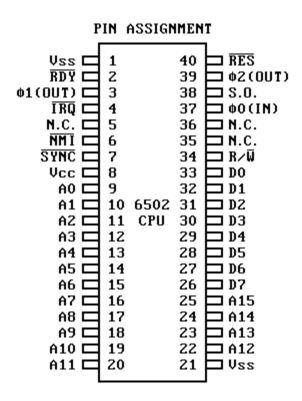
PIN	DESC	DESC	FUNCTION
1	CS	CHIP SELECT	A logic low on this input selects the chip and enable Host
			communication with the device.
2	R/W	READ/WRITE	EA logic high on this input controls the placement of data on the
			D0-D7 lines from a selected register, while a logic low causes a write
			operation to a selected register.
3,4	A0,A1	ADDRESS 0,1	These two inputs select a register to Read/Write data:

CS	A1	A0	R/W=1	R/W=0
0	0	0	Status Reg	Command Reg
0	0	1	Track Reg	Track Reg
0	1	0	Sector Reg	Sector Reg
0	1	1	Data Reg	Data Reg

5-12	DAL0-DAL7	DATA ACCESS LINES 0 THRU 7	Eight bit bidirectional bus used for transfer of data, control, or status. This bus is enabled by CS and R/W. Each line will drive one TTL load.
13	MR	MASTER RESET	A logic low pulse on this line resets the device and initializes the status register (internal pull-up).
14	GND	GROUND	Ground.
15	Vcc	POWER SUPPLY	$+5V \pm 5\%$ power supply input.
16	STEP	STEP	The STEP output contains a pulse for each step of the drive's R/W head. The WD 1770 and WD1772 offer different step rates.
17	DIRC	DIRECTION	The DIRECTION output is high when stepping in towards the center of the diskette, and low when stepping out.

18	CLK	CLOCK	This input requires a free-running 50% duty cycle clock (for internal timing) at 8MHz $\pm$ 1%.
19	RD	READ DATA	This active low input is the raw data line containing both clock and data pulses from the drive.
20	MO	MOTOR ON	Active high output used to enable the spindle motor prior to read, write or stepping operations.
21	WG	WRITE GATE	E This output is made valid prior to writing on the diskette.
22	WD	WRITE DATA	AFM or MFM clock and data pulses are placed on this line to be written on the diskette.
23	TR00	TRACK00	This active low input informs the WD1770 that the drive's R/W heads are positioned over Track Zero (internal pull-up).
24	IP	INDEX PULSE	This active low input informs the WD1770 when the physical Index Hole has been encountered on the diskette (internal pull-up).
25	WPRT	WRITE PROTECT	This input is sampled whenever a Write Command is received. A logic low on this line will prevent any Write Command from executing (internal pull-up).
26	DDEN	DOUBLE DENSITY ENABLE	This input pin selects either single (FM) or double (MFM) density. When DDEN = 0, double density is selected (internal pull-up).
27	DRQ	DATA REQUEST	This active high output indicates that the data register is full (on a READ) or empty (on a Write operation).
28	INTRQ	INTERRUPT REQUEST	This active high output is set at the completion of any command or reset or read of the status register.

## 6502 MICROPROCESSOR



PIN	DESC	FUNCTION
1,21	Vss	Ground.
2	RDY	Ready. TTL level input, used to DMA the 6502. The processor operates normally while RDY is high. When RDY makes a transition to the low state, the processor will finish the operation it is an, and any subsequent operation if it is a write cycle. On the next occurrence of read cycle the processor will halt, making it possible to tri-state the processor to gain complete access to the system bus.
3	Phi1	Phase 1 clock output.
4	IRQ	The Interrupt Request input is a request that the processor initiate an interrupt sequence. The processar will complete execution of the current instruction before recognizing the request. At that time, the interrupt mask in the Status Code Register will be examined. If the Interrupt Mask is not set, the processor will begin an interrupt sequence. The Program Counter and the Processor Status Register will be stored on the stack and the interrupt disable flag is set so that no other interrupts can occur. The processor will then load the Program Counter from the memory location \$FFFE and \$FFFF.
6	NMI	The Non-Maskable Interrupt Request is a negative-edge sensitive request that the processor initiate an interrupt sequence. The processor will complete execution of the current instruction before recognizing the request.
7	SYNC	The SYNC output is used in conjunction with RDY to allow single instruction execution.
8	Vcc	+5VDC input.
9-20,22-25	A0-A15	Address bus outputs. Unidirectional bus used to address memory and I/O devices.

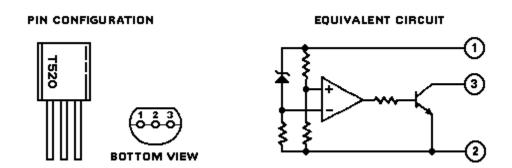
26-33	D0-D7	Bi-directional bus for transferring data to and from the device and the peripherals.
34	R/W	The read/write line is a TTL level output from the processor to control the direction of data transfer between the processor and memory, peripherals, etc. This line is high for reading memory and low for writing.
37	Phi0	Phase 0 clock input.
38	S.O.	Set Overflow flag. A negative going edge sets the overflow bit in the status code register.
39	Phi2	Phase 2 clock output.
40	RES	The Reset input is used to reset or start the microprocessor from a power down condition. During the time that this line is held low, writing to or from the microprocessor is inhibited. When a positive edge is detected on the input, the microprocessor will immediately begin the reset sequence. After a system initialization time af 6 cycles, the mask interrupt flag will be set and the processor will load the program counter from the contents of the memory location \$FFFC and \$FFFD. This is the start location for program control. After $V_{cc}$ reaches 4.75 volts in a power up routine, reset must be held low for at least 2 cycles. At this time the R/W line will become valid.

6522 VERSATILE INTERFACE ADAPTOR (VIA)

PI	N f	ASSIGN	IMEN	T	
PA0	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20	6522 VIA	40 39 38 37 36 35 34 33 32 31 30 29 28 27 26 25 24 22 21		CA1 CA2 RS0 RS1 RS2 RS3 RES D0 D1 D2 D3 D4 D5 D6 D7 Φ2 CS1 CS2 R \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \

PIN	DESC	FUNCTION
1	Vss	Ground.
2-9	PA0-PA7	Peripheral I/O Port A.
10-17	PB0-PB7	Peripheral I/O Port B.
18,19	CB1,CB2	Peripheral B Control Lines.
20	Vcc	+5VDC.
21	IRQ	Interrupt Request.
22	R/W	Read/Write.
23,24	CS1,CS2	Chip Select.
25	02	Phase 2 Internal Clock.
26-33	D0-D7	Data Bus.
34	RES	Reset Input, Low Active.
35-38	RS0-RS3	Register Select Inputs.
39,40	CA1,CA2	Peripheral A Control Lines

T520 VOLTAGE DETECTOR I.C.



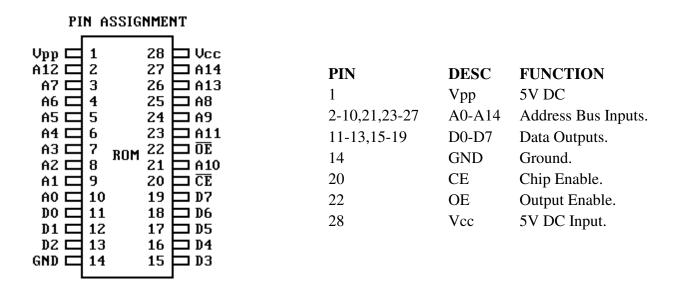
## 6526/8520 COMPLEX INTERFACE ADAPTOR (CIA)

Vss 1 40 CNT PA0 2 39 SP	]
PA1	PA0

PIN	DESC	FUNCTION
1	Vss	Ground.
2-9	PA0-PA7	Parallel port A signals. Bi-directional parallel port.
10-17	PB0-PB7	Parallel port B signals. Bi-directional parallel port.
18	PC	Handshake output. A low pulse is generated after a read or write on port B.
19	TOD	Time of day clock input. Programmable 50Hz or 60Hz input.

20	Vcc	5V DC input.
21	IRQ	Interrupt output to microprocessor.
22	R/W	READ/WRITE input from microprocessor's R/W output.
23	CS	Chip select input. A low pulse will activate CIA.
24	FLAG	Negative-edge sensitive interrupt input. Can be used as a handshake line for either
		parallel port.
25	Phi2	Phase 2 clock input.
26-33	DB0-DB7	Bi-directional data bus.
34	RES	Low active reset input. Initializes CIA.
35-38	RS0-RS3	Register select inputs. Used to select all internal registers for communications with
		the parallel ports, time of day clock, and serial port (SP).
39	SP	Serial Port bi-directional connection. An internal shift register converts
		microprocessor parallel data into serial data, and visa-versa.
40	CNT	Count input. Internal timers can count pulses applied to this input. It is used for
		frequency dependent operations.

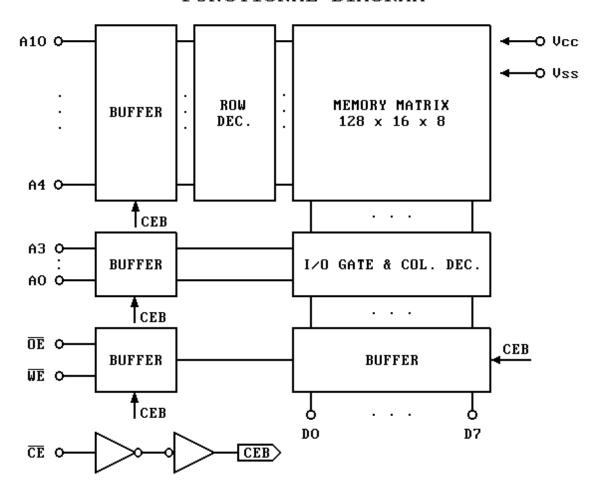
## 23256 32K x 8 ROM



## 2016 2K x 8 STATIC RAM

PI	N AS	SSIGN	MEI	NT			
				1	PIN	<b>DESC</b>	FUNCTION
A7 □ A6 □	1 2		24 23	Vcc A8	1-8,19,22,23	A0-A10	Address Bus Inputs.
A5	3		22	H <sub>A9</sub>	9-11,13-17	D0-D7	Common Data Input/Output Lines.
A4 □	4		21	i <u>we</u>	12	Vss	Ground.
A3 🗆 A2 🗆	5 6		20 19	DE HA10	18	CS	Chip Select Enable, Low Active.
H2	7	RAM	18	E <sup>nt</sup> o	20	OE	Output Enable,
A0 🗀	8		17	□ D7			Low Active.
D0 🗆	9		16	₽ <u>06</u>	21	WE	Write (Input) Enable,
D1 🗆 D2 🗖	10		15	D5 D4			Low Active.
Vss 🗆	11 12		14 13	<b>5</b> 03	24	Vcc	5V DC Input.

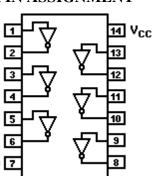
#### FUNCTIONAL DIAGRAM



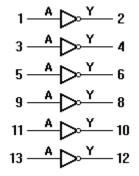
## **COMMON I.C.'S** PIN ASSIGNMENTS AND LOGIC

7406 HEX INVERTER BUFFER/DRIVER (OPEN COLLECTOR)





#### LOGIC DIAGRAM

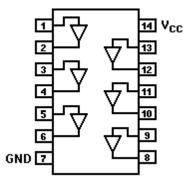


#### TRUTH TABLE

INPUT	OUTPUT
A	Y
Н	L
L	Н

#### 7407 HEX BUFFER/DRIVER (OPEN COLLECTOR)





#### LOGIC DIAGRAM

$$\begin{array}{c|cccc}
1 & A & Y & 2 \\
3 & A & Y & 4 \\
5 & A & Y & 6 \\
9 & A & Y & 8 \\
11 & A & Y & 10 \\
13 & A & Y & 12
\end{array}$$

#### TRUTH TABLE

INPUT	OUTPUT
$\mathbf{A}$	Y
Н	Н
L	L

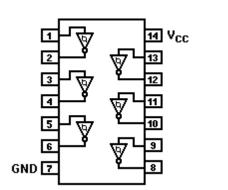
7414 • 74LS14 • 74F14 HEX INVERTER SCHMITT TRIGGER

PIN ASSIGNMENT

LOGIC DIAGRAM

**TRUTH TABLE** 

INPUT	OUTPUT
A	Y



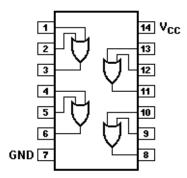
1-	A > Y 2
3 —	A Y 4
5 –	A > Y 6
9 –	A Y 8
11 –	A Y 10
13 –	A Y 12

L	Н
Н	L

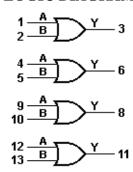
## COMMON I.C.'S PIN ASSIGNMENTS AND LOGIC

7432 • 74S32 • 74LS32 • 74F32 QUAD 2-INPUT OR GATE

#### PIN ASSIGNMENT



#### **LOGIC DIAGRAM**



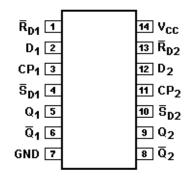
#### TRUTH TABLE

INPUTS		OUTPUT
A	В	Y
L	L	L
L	Н	Н
Н	L	Н
Н	Н	Н

H = HIGH voltage level L = LOW voltage level

7474 • 74S74 • 74LS74 • 74F74 DUAL D-TYPE FLIP-FLOP (POSITIVE EDGE TRIGGERED)

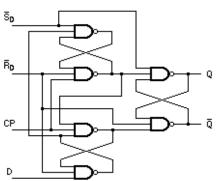
#### PIN ASSIGNMENT



#### TRUTH TABLE

		INPUTS				OUTPUTS	
OPERATING MODE	$ar{\mathbf{s}_{\mathbf{D}}}$	$ar{ extbf{R}_{ extbf{D}}}$	СР	D	Q	Q	
Asyn. Set	L	Н	X	X	Н	L	
Asyn. Reset (Clear)	Н	L	X	X	L	Н	
Undetermined (a)	L	L	X	X	Н	L	
Load "1" (Set)	Н	Н	<b>↑</b>	h	Н	L	
Load "0" (Reset)	H	Н	1	1	L	Н	

#### LOGIC DIAGRAM



H = HIGH voltage level steady state.

h = HIGH voltage level one setup time prior to the LOW-to-HIGH clock transition.

L = LOW voltage level steady state.

l = LOW voltage level one setup time prior to the LOW-to-HIGH clock transition.

X = don't care.

 $\uparrow$  = LOW-to-HIGH clock transition.

#### NOTE

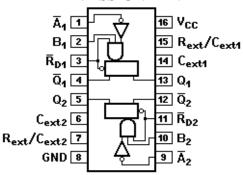
(a) Both outputs will be HIGH while both SD and RD are LOW.

But the output states are unpredictable if SpandRpgo HIGH simultaneously.

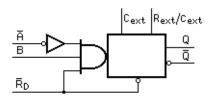
#### 74123 • 74LS123

#### DUAL RETRIGGERABLE MONOSTABLE MULTIVIBRATOR

#### PIN ASSIGNMENT



#### LOGIC DIAGRAM



#### TRUTH TABLE

INPUTS			OUTPUTS		
$ar{ extbf{R}_{ extbf{D}}}$	Ā	В	Q	$ar{ extbf{Q}}$	
L	X	X	L	Н	
X	Н	X	L	Н	
X	X	L	L	Н	
Н	L	1	Т	工	
Н	1	H	$\Gamma$	1.5	
<b>↑</b>	L	H	J L		

H = HIGH voltage level

L = LOW voltage level

X = Don't care

 $\uparrow$  = LOW-to-HIGH transition

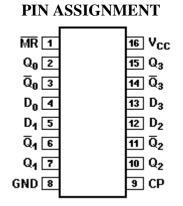
 $\downarrow$  = HIGH-to-LOW transition

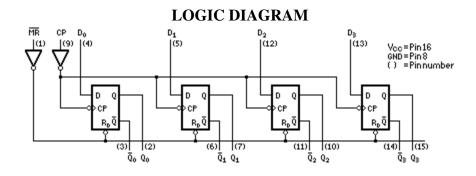
□ = One HIGH-level pulse

∟ = One LOW-level pulse

## COMMON I.C.'S PIN ASSIGNMENTS AND LOGIC

#### 74175 • 74LS175 • 74F175 QUAD D-TYPE FLIP-FLOP





#### TRUTH TABLE

<b>OPERATING</b>	IN	INPUTS			OUTPUTS	
MODE	MR	CP	Dn	Qn	$ar{\mathbf{Q}}_{\mathbf{n}}$	
Reset (clear)	L	X	X	L	Н	
Load "1"	Н	1	h	Н	L	
Load "0"	Н	T	1	L	Н	

H = HIGH voltage level steady state.

h = HIGH voltage level one setup time prior to the LOW-to-HIGH clock transition.

L = LOW voltage level steady state.

l = LOW voltage level one setup time prior to the LOW-to-HIGH clock transition.

 $\uparrow$  = LOW-to-HIGH clock transition.

X = don't care.

## 74LS241 • 74F241 OCTAL BUFFER, TRI-STATE

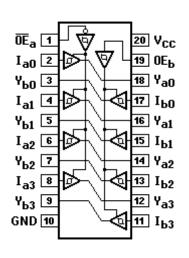
PIN ASSIGNMENT

LOGIC DIAGRAM

#### TRUTH TABLE

INPUTS				OUT	PUTS
$\overline{OE}_a$	Ia	OE <sub>b</sub>	I <sub>b</sub>	Ya	Yb
L	L	Н	L	L	L
L	Н	Н	Н	Н	Н
Н	X	L	X	(Z)	(Z)

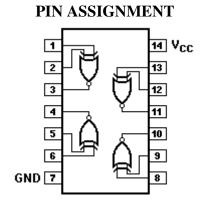
H = HIGH voltage level L = LOW voltage level

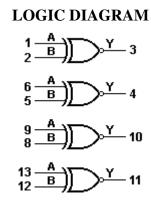


2	Ia	<b>-</b>	<mark>Уа</mark> 18
4	Ia	$\triangleright$	Y <sub>a</sub> 16
6	I <sub>a</sub>		Υ <sub>а</sub> 14
8	I <sub>a</sub>		Υ <sub>а</sub> 12
9	<u>ŌĒ</u> a_o		
17	I <sub>b</sub>	<b>~</b> ┣─	<mark>У</mark> Ь 3
17 15	I <sub>b</sub>		Υ <sub>Ь</sub> 3
15	Iь		<mark>У</mark> Ь 5

X = Don't care (Z) = HIGH impedance (off) state

## 74LS266 QUAD 2-INPUT EXCLUSIVE NOR GATE (OPEN COLLECTOR)





#### TRUTH TABLE

INPUTS		OUTPUT
A	В	Y
L	L	Н
L	Н	L
Н	L	L
Н	Н	Н

H = HIGH voltage level L = LOW voltage level

## PARTS LIST PCB ASSEMBLY #310420

Commodore part numbers are provided for reference only and do not indicate the availability of parts from Commodore. Industry standard parts (Resistors, Capacitors, Connectors) should be secured locally. Approved cross-references for TTL-chips, Transistors, etc. are available in manual form through the Service Department, order part #314000-01. Unique or non-standard parts will be stocked by Commodore and are indicated on the parts list by a "C". Vendor Name and part number have been provided for your convenience in ordering custom or unique parts.

U1	6502 CPU	C 901435-01
U2	23256 ROM	C 310654-03
U3	2016 RAM 200 NS	
U4	65C22A VIA 2MHZ	C 310653-01
U5	Gate Array 20 Pin	C 251829-01
U6	Gate Array 40 Pin	C 251828-01
U7	R/W Hybrid	C 251853-01
U8	7406	
U9	65C22A VIA 2MHZ	C 310653-01
U10	74LS74	
U11	WD 1770 Disk Control	C 310651-01 sub:
	WD 1772 Disk Control	C 310651-02
U12	74F32	
U13	74LS266	
U14	7407	
U15	74LS14	
U16	7406	
U17	74LS14	
U18	74LS175	
U19	74LS241	
U20	6526 CIA 2MHZ	C 906108-02 sub:
	8520 CIA 2MHZ	C 318029-02
U21	PST 520C/D Volt Detector	or C 252034-02
U22	74LS123	
TRA	NSISTORS	
Q1	MPSU51 PNP	

RESI	STORS (Continued)
R14,15	5 2.7k
R16,17	′ 4.7k
R18,19	9 47
R20	20k
R21	4.7k
R22	1k
R23	390
R24	47
R25-28	3 2k
R29	4.7k
R30	15k
R31	2k
R32	4.7k
R33-35	5 2.7k
R36-38	3 1k
R39	43k
R40	4.7k
CAPA	ACITORS
C1-20	Ceramic .1 µF 16V
C21	Electrolytic $_{\mu F}^{10}$ 25V

.1 μF 16V

.1 μF 16V

 $50V \pm 5\%$ 

10V +50%/-10%

C22,23 Ceramic

**NPO** 

Ceramic

Electrolytic

C24

C27

C28

Q2,3,7 2SC1815 NPN
Q4 2SA673 PNP
Q5 2SC945 NPN sub:
2SC1685 R,S
Q7 2SC1815 NPN

#### **DIODES**

CR3-8 Signal 1N914 CR10 Signal 1N4002 CR11 Zener 3.3V

# **RESISTORS** - All are carbon 1/4 watt, 5% unless noted otherwise

R1-3 47 R4 4.7k R5 390 1/2W ±5% R6 1.2k R7,8 1k R9-11 47k R12 150 R13 390 C29 Electrolytic  $\frac{10}{\mu F}$  25V

C31 Electrolytic 1  $\mu F$  16V

C32 Ceramic  $\frac{.01}{\mu F}$  50V

C33 Tantalium 1  $\mu F$  35V ± 10%

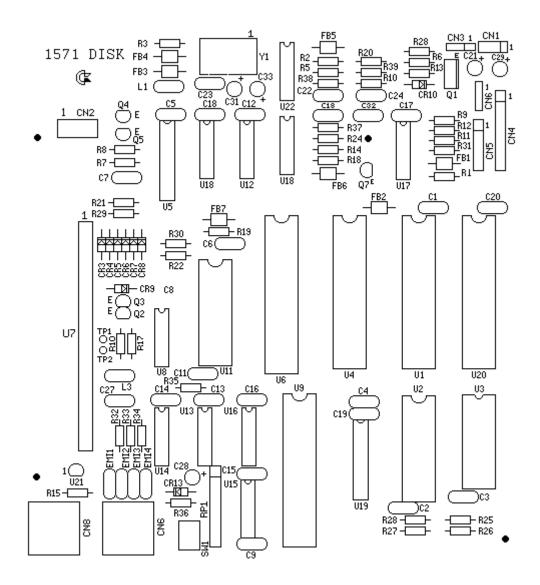
#### **MISCELLANEOUS**

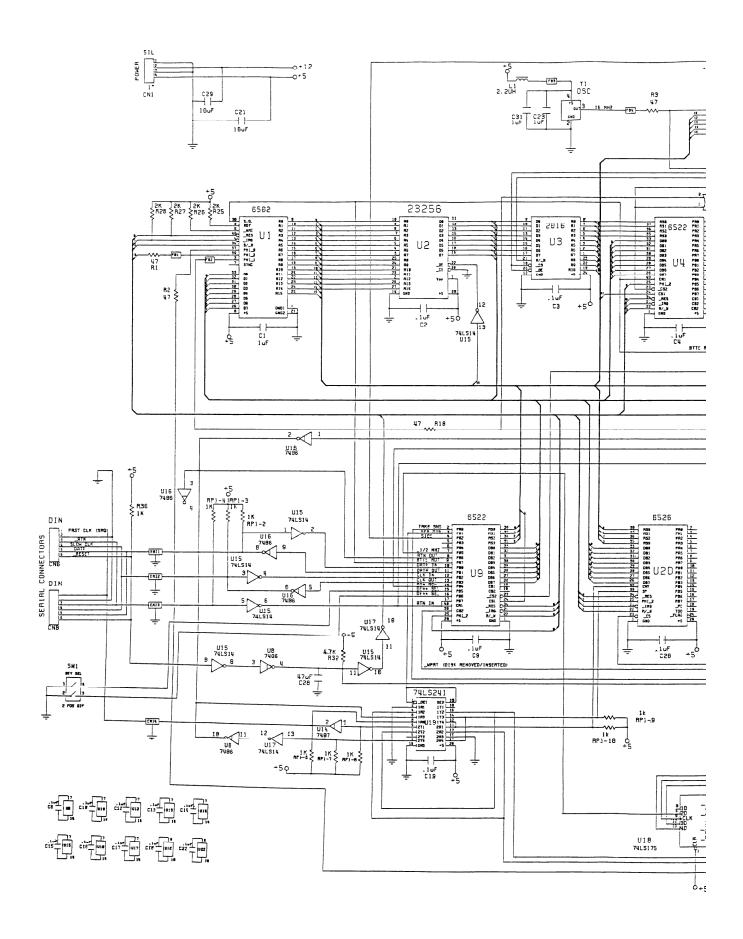
**EMI** Ferrite Bead 1-4 FB 1-7 Ferrite Bead L1 Coil Inductor 2.2 µH Coil Inductor 100 µH L3 Resistor Pack 1k, 10Pin RP1 4 Pos Dip Switch SW1 C 252144-02 **Y**1 Crystal Module 16MHZ C 325566-01

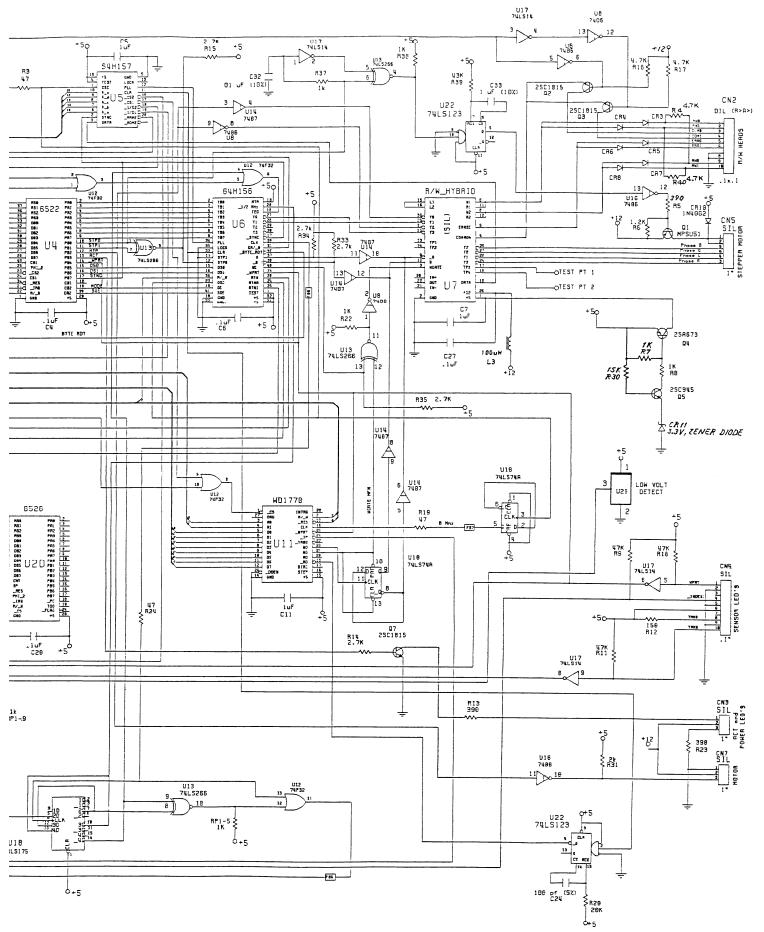
#### **CONNECTORS**

CN1	Header Assy, 4Pin (Molex 3022-04A, AMP 640098-4)
CN2	Header Assy, Dual RT Angle 10Pin
CN3	Header Assy, 3Pin (Molex 3022-03A, AMP 640098-3)
CN4	Header Assy, 10Pin (Molex 3022-10A, AMP 1-640098-0)
CN5	Header Assy, 6Pin (Molex 3022-06A, AMP 640098-6)
CN6,8	Connector, 6Pin Din, Shielded C252166-01
CN7	Header Assy, 3Pin (Molex 3022-03A, AMP 640098-3)

## PCB ASSEMBLY #310420 BOARD LAYOUT







PCB ASSEMBLY #310420 SCHEMATIC